Shivam Sood

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➡ Shivam Sood

EDUCATION

Indian Institute of Technology Kharagpur

West Bengal, India

Integrated Masters in Mechanical Engineering - GPA: 8.59

Jul 2019 - Present

Bhupendra International Public School

Patiala, India Apr 2019

High School: 91.8%, Secondary School - GPA: 10.0

Publications

[1] DecAP : Decaying Action Priors for Accelerated Learning of Torque-Based Legged Locomotion Policies

Shivam Sood, Ge Sun, Peizhuo Li, Guillaume Sartoretti Accepted at IROS 2024 [link]

[2] Force control for Robust Quadruped Locomotion: A Linear Policy Approach Aditya Shirwatkar, Vamshi Kumar Kurva, ..., Shivam Sood, ..., Shishir Kolathaya Accepted at ICRA 2023 [link]

[3] Multiple Waypoint Navigation in Unknown Indoor Environments
Shivam Sood, Jaskaran Singh Sodhi, Parv Maheshwari, Karan Uppal, Debashish Chakravarty
Accepted at ICCR 2022 [link]

EXPERIENCE

Research Intern

Multi-Agent Robotic Motion Laboratory

NUS, Singapore

Mar 2023 – Present

- Designed a novel action priors framework for accelerated learning of torque-based legged locomotion policies
- Developed a sim-to-real method utilizing low-gain position PID control for scalable torque-based control
- Implemented model-free position control policy, trained using PPO in Isaac Gym, on a hexapod robot(Daisy)

Stochastic Robotics Lab

IISc Bangalore

Research Intern

May 2022 – Dec 2022

- Implemented a motion imitation based linear RL policy on an in-house quadruped (Stoch3) using PGPE
- Applied Representation-Free MPC for stable trajectory tracking of a quadruped achieving frequencies of 60Hz
- Worked on lower-level motor control for swing and stance legs calculating the feedback and feedforward torques

Autonomous Ground Vehicle Research Group

IIT Kharagpur

Undergraduate Researcher

Mar 2020 – Present

- Benchmarked and tested Control algorithms like Stanley, Pure Pursuit, Pole Placement, LQR and MPC
- Optimized control algorithms for compute and performance utilizing adaptive cost and path velocity profiling

Vecros Technologies Private Limited

New Delhi, India

Robotics Software Development Intern

May 2021 – Jul 2021

- Implemented Dijkstra-based path planning algorithm for a multi-agent system of drones in a 3D weighted grid
- Deployed YOLO algorithm on RealSense cameras with integrated Kalman Filtering for trajectory detection of a car

Projects and Competitions

DRDO UAV-Guided UGV Navigation Challenge

DRDO & IIT Kharagpur

Winner, Inter IIT Tech. Meet 10.0 [Presentation]

Mar 2022

- Secured first position representing IIT Kharagpur, outperforming 22 other IITs with more than a 10% margin
- Implemented NMPC control for an unmanned snow-clearing ground vehicle on mountains with steep slopes
- Used a UAV's vision data for state feedback along with automated coordinated motion of the UAV and the UGV

Navigation and Manipulation in Unknown Environments

Winner, IROS-RSJ Navigation and Manipulation Challenge 2021 [Link]

Prague, Czech Republic Jul 2021 – Sep 2021

- Utilized LiDAR, GPS and IMU based exploration and mapping for real-time obstacle avoidance and control
- Implemented MPC algorithm with optimizations including adaptive tuning and an adaptive path resolution
- Integrated global and local planning modules for TiaGO Base bot to traverse multiple waypoints in shortest time

Unmanned Rover for Astronaut Assistance

IIT Kharagpur

University Rover Challenge 2022 — Guide: Prof Debashish Chakravarty

Mar 2020 - Dec 2021

- Developed a chassis and **rocker-bogie suspension** system for rover prototype for the University Rover Challenge
- Performed static and dynamic simulations of the rover to optimize for load carrying, gradeability, and handling

ACHIEVEMENTS

COMPETI	TIONS	
2023	Winner, in Inter IIT Tech Meet 11.0	Drona/IIT Kanpur
2022	Quarter Finalist, in ICRA F1Tenth Challenge [Results: Team AGV]	Philadelphia, PA
2022	Winner, in Inter IIT Tech Meet 10.0 [Certificate]	DRDO/IIT Kharagpur
2021	Winner, in IROS Navigation and Manipulation Challenge [Certificate]	Prague, Czech Republic
ACADEMI	C ACHIEVEMENTS	
2023	Recipient of the Technology Alumni Cup	IIT Kharagpur
2019	Ranked in Top 1.4%, out of 0.2 million candidates	JEE (Advanced) 2019
2019	Ranked in Top 0.2%, out of 1.3 million candidates	JEE (Main) 2019

TECHNICAL SKILLS

Languages	C, C++, Python, MATLAB, AVR (Assembly), Arduino, LaTeX
Libraries	SciPy, NumPy, OpenAI/Gym, CasADi, qpSWIFT, Pytorch, Matplotlib
Frameworks/CAD	Git, ROS1, ROS2, Solidworks, Ansys, MavROS, ArduPilot, Mission Planner
Simulation/Miscellaneous	Gazebo, Rviz, Webots, LTSpice, Adobe Photoshop, Adobe Premiere Pro

Relevant Coursework

* INDICATES MOOC

Robotics	<u>Control of Mobile Robots</u> *, Reinforcement Learning*, Controls Bootcamp*, Robotics			
Mechatronics Kinematics and of Machines, Dynamics of Machines, Basic Electronics, Rapid Prototyping				
Software	Deep Learning*, Intelligent Machines and Systems, Soft Computing, Programming and Data Structures			

Position of Responsibility

Captain, Drona Aviation Pluto Swarm Drone Challenge

IIT Kharagpur

Inter IIT Tech. Meet 11.0

Dec 2022 - Present

• Led a team of 15 undergraduate students with the aim of developing a vision-based state feedback control for an indoor multi-drone system handling socket communication with the flight controller without the use of ROS

Tutor, Autonomous Robotics

IIT Kharagpur

IEEE Winter School of Robotics [Certificate]

Mar 2021

• Mentored a batch of 100+ students, focusing on various aspects of robotics including micro-controllers, AVR programming, sensor integration, basic algorithms for control of mobile robots, and Robot Operating System

Freshmen Mentor

IIT Kharagpur

Student Welfare Group [Certificate]

 $May\ 2021-Present$

• Mentoring five junior students of my department throughout their college life for general and academic doubts

EXTRACURRICULARS

National Cadet Corps - Participated in parades, blood-donation camps, marathons, and arms training Football - Represented my hall at the Inter-hall Football Championship 2022 among 21 participating halls Digital Art - Avid digital artist interested in stylized portraits, with a following of more than 500 people